FAHER E-ARRAS

Essential Settings:

Step 1 to 3 must be completed to ensure proper operation.

1) First methode pairing

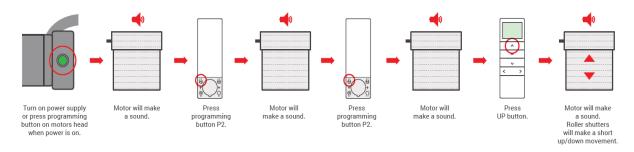


If on the right press the P2 —P2—UP button



If on the left press the P2 —P2 —DOWN button.

2) Second methode pairing



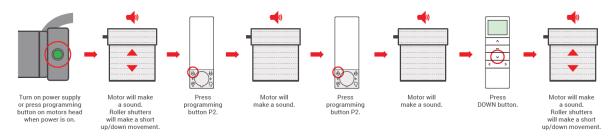
3) Switch Rotating Direction 1 METHOD

Press UP and DOWN motor runs downwards, try below to switch direction

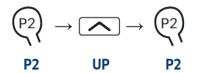


Press and hold UP and DOWN buttons simultaneously for 2 s, motor jog once, the direction has been switched successfully.

4) Switch Rotating Direction 2 METHOD

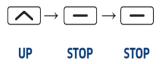


5) Programming limit positions



Press P2 (1 beep and 1 jog), UP (1 beep and 1 jog), and P2 (3 beeps and 1 jog), motor is ready for limit settings.

Set upper limit



Press UP, operate the motor to desired upper position, press STOP once, then press and hold STOP for 5 s (3 beeps and 1 jog), upper limit is set.

Hold STOP or press STOP 5 times until the engine approves the command

Set lower limit



Press DOWN, operate the motor to desired lower position, press STOP once, then press and hold STOP for 5 s (3 beeps and 1 jog), lower limit is set.

Hold STOP or press STOP 5 times until the engine approves the command

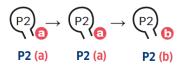
If the engine works in jump mode after setting the end positions, see point 6

6) Activate / Deactivate Jog / Tilt Mode



Press P2 (1 beep and 1 jog), UP (1 beep and 1 jog), DOWN (make a long noise and 1 jog), Jog / tilt mode is deactivate. If motor beep 3 times and jogs 3 times, Jog / tilt mode is activated.

7) Pair Additional Emitter



Press P2 (1 beep and 1 jog) and P2 (1 beep and 1 jog) on existing emitter, press P2 on new emitter to add (3 beeps and 1 jog), new emitter is paired to the motor.

• Repeat same procedure will unpair additional emitter.

8) Remove All Emitters



STOP

Press P2 (1 beep and 1 jog), STOP (1 beep and 1 jog), and P2 (3 beeps and 1 jog), all settings are deleted.

9) Deleting All Limits



DOWN

Press P2 (1 beep and 1 jog), DOWN (1 beep and 1 jog), and P2 (3 beeps and 1 jog). all limits are removed.

^{*} Press **UP** or **DOWN** for more than 2 s, the motor continues run; It must be done after setting the upper limit and the lower limit; Close the jog & tilt function, the motor running continuously.

^{* (}a) as existing emitter, (b) as new emitter to pair/unpair.

^{*}After deleting all emitters, keep the original limit information.

QUICK INDEX

Settings		Steps
Pairing	P2 → P2 → UP	
Switch Rotating Direction	UP + DOWN (hold down 2 s)	
	Initiate limit setting	$P2 \rightarrow UP \rightarrow P2$
	Set upper limit	UP → STOP → STOP (hold down 5 s)
Upper and Lower Limits Setting	Set lower limit	DOWN → STOP → STOP (hold down 5 s)
Adjust Limits	Adjusting the upper limit position	UP → UP + DOWN (hold down 5 s) → UP or DOWN → \rightarrow STOP (hold down 5 s)
	Adjusting the lower limit position	DOWN \rightarrow UP + DOWN (hold down 5 s) \rightarrow UP or DOWN \rightarrow \rightarrow STOP (hold down 5 s)
Activate / Deactivate Jog / Tilt Mode	$P2 \to UP \to DOWN$	
Pair / Unpair Additional Emitter	P2 (a) → P2 (a) → P2 (b)	
Remove All Emitters	$P2 \to STOP \to P2$	
Delete All Limits	P2 → DOWN → P2	
Adding Wind-sun Sensor	P2 (a) → P2 (a) → P2 (wind-sun sensor)	
Enable / Disable Sun Detection	Enable sun detection	UP + STOP
	Disable sun detection	DOWN + STOP